Universidad de @UCLM Castilla-La Mancha

A comparative study of machine learning, deep neural networks and random utility maximization models for travel mode choice modelling



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Introduction

Discrete Choice Models

Random Utility Theory (RUM)

- Have dominated travel behaviour researches since 1970s.
- Have acquired a high degree of sophistication.
- Are highly interpretable.
- Requires to specify a functional expression beforehand.

Artificial Intelligence

Machine Learning (ML)

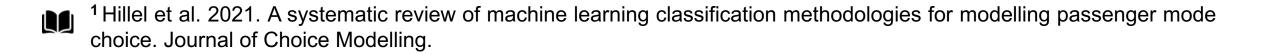
- Successful application to many areas.
- Alternative to RUM to model individual behaviour.
- More precision and no functional expression.
- Black-box models: Difficult to interpret.

Introduction

Hillel et al. (2021): The methodologies in the literature are highly fragmented and there are technical limitations which makes difficult to asses properly ML models in choice modelling.

In this study:

- Comprehensive comparison
- Systematic assessment
- Two dataset of a completely different nature
 - > 1.900 obs.
 - > 230.000 obs.



Related work

In existing literature, RUM and ML methods are compared from two points of view:

> Behavioural interpretation in a context of discrete choice modelling.

Assessment of the performance of the models.

| Reference | Domain | RUM Neural networks | | | Single classifiers | | | Ensembles | | | | | |
|---------------------------------|-----------------------------------|----------------------------|----|-----|--------------------|-----|-----|-----------|------|-------|-----|----|-----|
| | | MNL | NN | DNN | CNN | KNN | SVM | NB | CART | BOOST | BAG | RF | KF |
| Zhao et al. (2018) | Travel mode choice | x | x | | | | x | x | х | • | • | • | 1.2 |
| Lhéritier et al. (2019) | Airline itinerary choice modeling | x | | | | | | | | | | • | |
| Hagenauer and Helbich (2017) | Travel mode choice | x | x | | | | • | x | | x | x | • | |
| Omrani (2015) | Travel mode choice | x | • | | | | x | | | | | | |
| Ballings et al. (2015) | Stock price direc- tion | x | x | | | x | • | | | x | | • | x |
| This study | Travel mode choice | x | x | • | • | | x | | | | | • | |

² Zhao et al. 2018. Modeling Stated Preference for Mobility-on-Demand Transit: A Comparison of Machine Learning and Logit Models.

³ Lheritier et al. 2019. Airline itinerary choice modeling using machine learning. Journal of Choice Modelling.

⁴ Hagenauer and Helbich 2017. A comparative study of machine learning classifiers for modeling travel mode choice. Expert Systems with Applications.

⁵ Omrani 2015. Predicting travel mode of individuals by machine learning. Transportation Research Procedia.

⁶ Ballings et al. 2015. Evaluating multiple classifiers for stock price direction prediction. Expert Systems with Applications.

Methodology: Datasets

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OPTIMA

- Revealed preferences survey to Swiss people from 2009 to 2010.
- 1124 surveys with 115 variables \rightarrow 1906 trips.
- After pre-processing, 7 variables selected.







NTS

- ML focused dataset containing:
 - Data from a Dutch transport survey from 2010 to 2012.
 - Environmental data.
- 230.608 surveys with 16 variables.
- After pre-processing, 100.000 trips where randomly selected.











Multinomial Logit Model (MNL)

- Utility functions: $U_{in} = V_{in} + \epsilon_{in}$ •
- Stochastic part determines the probability of alternative *i*: $P_{in} = \frac{\exp(V_{in})}{\sum_{i \in C} \exp(V_{in})}$ •
- Deterministic part: •
 - For NTS dataset: $V_{in} = \beta_i^T \mathbf{x}_{in}$
 - For OPTIMA: Bierlaire (2018)

$$V_{PT} = \beta_{\text{Time}_PT} * \text{Time}PT + \beta_{\text{Cost}_PT} * \text{MarginalCostPT} + \beta_{\text{Fulltime}_PT} * \text{Fulltime} + \beta_{\text{Man}_PT} * \text{Man} + \beta_{\text{Woman}_PT} * \text{Woman} + \beta_{\text{Unreported}_PT} * \text{Unreported}$$

$$V_{Car} = \beta_{ASC_Car} + \beta_{Time_Car} * TimeCar + \beta_{Cost_Car} * CostCarCHF + \beta_{Fulltime_Car} * Fulltime + \beta_{Man_Car} * Man + \beta_{Woman_Car} * Woman + \beta_{Unreported_Car} * Unreported$$

$$W_{SM} = \beta_{ASC_SM} + \beta_{Dist} * distance_km + \beta_{Fulltime_SM} * Fulltime + \beta_{Man_SM} * Man + \beta_{Woman_SM} * Woman + \beta_{Unreported_SM} * Unreported$$





Neural Network (NN)

- Multilayer Perceptron (MLP) is a widely used NN in classification problems.
- A MLP with 1 hidden layer can model any non-linear relationship between the input variables and the target.
- Backpropagation algorithm is used to minimise the log-loss function.
- The output of the model is a vector of probabilities per alternative:

$$P(y_k|x) = s' \left\{ \sum_{j=1}^{n_2} \omega_{jk} \cdot s \left\{ \sum_{i=1}^{n_1} \omega_{ij} \cdot x_i + b_{0j} \right\} + b_{0k} \right\}$$

- ω : weights
- *s* and *s*': activation functions (ReLU)
- n_1 and n_2 : number of neurons in the layer



Deep Neural Network (DNN)

- Consists in adding multiple hidden layers to a MLP.
- It improves the predictive capability on problems with non-structure data or high non-linearities.
- We have used a DNN model with 3 hidden layers of 64 neurons.

Convolutional Neural Network (CNN)

- They are based on the concept of filter (kernel).
- They are especially effective where features from different abstraction levels must be extracted.
- The kernels are two-dimensional in the case of images. In this study, since we work with matrix data, we apply a one-dimensional convolution.
- We have used a CNN model with 3 one-dimensional convolution layers of 64 kernels with a size of two units.



Random Forest (RF)

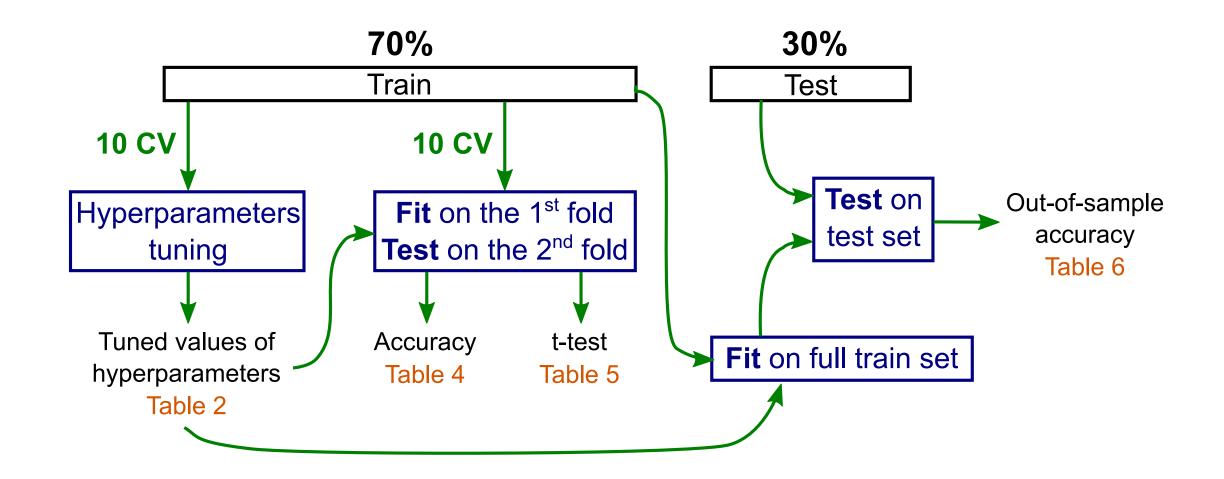
- Consists on tree-like data structures used for classification tasks.
- Each node of the tree represent a binary decision. The leaves are the alternatives.
- A RF is an ensemble composed of several different trees, using a subset of the features for each tree to improve the accuracy.



Support Vector Machine (SVM)

- A binary SVM assumes that the data can be labelled as $y_n \in \{-1, 1\}$.
- Then, it builds a decision function $f(x) = \operatorname{sgn}(\sum_{n=1}^{N} y_n \alpha_n K(x_n, x) + \rho)$ where $K(x_n, x)$ is a kernel function. We apply the RBF kernel.
- Then, the vector α_n is estimated.
- For multiclass problems (I alternatives), we estimate $\frac{I(I-1)}{2}$ binary SVM.

Methodology



Methodology: Hyperparameters

• We formulate a Hyperparameter Optimization problem:

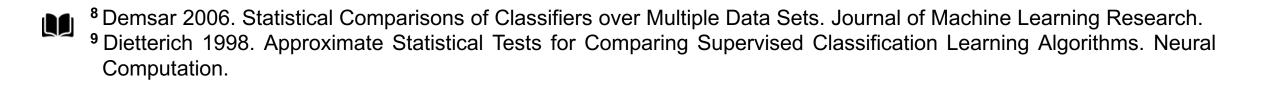
 $\lambda^* = \underset{\lambda \in \Lambda}{\operatorname{argmin}} \mathbb{E}_{(D_{train}, D_{valid}) \sim \mathcal{D}} \mathbf{V}(\mathcal{A}_{\lambda}, D_{train}, D_{valid}),$

• Random search with 1.000 iterations with 10 CV to estimate V.

| Technique A | Name of the hyperaparameter | Notation | Туре | Domain | OPTIMA | NTS |
|-------------|--|----------|------------|------------------------|--------|--------|
| SVM | The parameter of the Gaussian function | σ | Continuous | [10 ⁻⁴ , 1] | 0.145 | 0.031 |
| | The cost or also called soft margin constant | C | Continuous | [1, 10 ³] | 10.678 | 10.973 |
| RF | Number of decision trees | B | Discrete | [2, 200] | 192 | 186 |
| | Max features | m | Discrete | [2, N features] | 6 | 3 |
| NN | Size of hidden layer | P | Discrete | [10, 500] | 11 | 423 |
| | Initial learning rate | η_n | Continuous | [10 ⁻⁴ , 1] | 0.072 | 0.044 |
| DNN | Epochs | epochs | Discrete | [50, 200] | 186 | 198 |
| | Batch size | BS | Discrete | [1, DatasetRows] | 393 | 951 |
| CNN | Epochs | epochs | Discrete | [50, 200] | 190 | 120 |
| | Batch size | BS | Discrete | [1, DatasetRows] | 78 | 200 |

Methodology: Model comparison

- There is no golden standard for comparing classifiers.
- The most widely used index is classification accuracy (Demsar, 2006).
- In most of studies on transport mode choice, only one dataset is used.
- The standard way of assessing the classifiers on a single dataset is using cross-validation (CV).
- In this paper we follow Dietterich (1998) and propose a 5x2 CV over each dataset.
- Moreover, this methodology allows us to apply a t-test to the results (Dietterich, 1998).





- All the experiments have been implemented in Python.
- RF, SVM, and NN methods have been executed using scikit-learn package.
- For DNN and CNN we have apply Keras Python library.
- MNL model has ben implemented on PyKernelLogit (Martín-Baos, 2019).
- Finally, hyperopt package was used to tune hyperparameters.

• To address class imbalance, a re-sampling procedure was applied to NTS dataset, which is a common procedure in ML.



¹⁰ Martín-Baos 2019. Design and implementation of a software library for the estimation and analysis of non-parametric discrete choice models. Application to transport planning. Technical Report. Universidad de Castilla-La Mancha.

Results

| Dataset | | MNL | RF | SVM | NN | DNN | CNN |
|---------|--------------|------------------|------------------|--------------------|------------------|------------------|---------------------|
| OPTIMA | Accuracy | 0.713 | 0.753 | 0.746 | 0.742 | 0.757 | 0.744 |
| | 95% CI | [0.683 , 0.743] | [0.732 , 0.775] | [0.725 , 0.767] | [0.708 , 0.776] | [0.742 , 0.772] | [0.701 , 0.787] |
| | CPU time (s) | 0.178 | 0.463 | 0.013 | 0.088 | 1.757 | 6.513 |
| | 95% CI | [0.159 , 0.196] | [0.402 , 0.524] | [0.012 , 0.015] | [0.037 , 0.138] | [1.45 , 2.064] | [6.037 , 6.99] |
| NTS | Accuracy | 0.531 | 0.687 | 0.558 | 0.593 | 0.580 | 0.590 |
| | 95% CI | [0.526 , 0.536] | [0.682 , 0.691] | [0.551 , 0.565] | [0.527 , 0.658] | [0.556 ,0.604] | [0.572 , 0.607] |
| | CPU time (s) | 16.905 | 1.167 | 48.922 | 10.742 | 35.127 | 134.065 |
| | 95% CI | [9.849 , 23.961] | [1.166 , 1.169] | [47.881 , 49.962] | [5.427 , 16.057] | [33.924 , 36.33] | [127.653 , 140.478] |

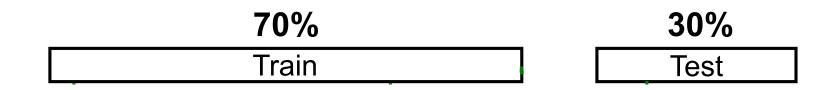
Results: Significance t-test

P-value and significance t-test results

| Dataset | | MNL | RF | SVM | NN | DNN | CNN |
|---------|-----|-----|-------|-------|-------|-------|-------|
| | MNL | | 0.000 | 0.000 | 0.001 | 0.000 | 0.002 |
| | RF | *** | | 0.164 | 0.114 | 0.460 | 0.270 |
| | SVM | *** | | | 0.553 | 0.024 | 0.810 |
| OPTIMA | NN | ** | | | | 0.032 | 0.822 |
| | DNN | *** | | * | * | | 0.120 |
| | CNN | ** | | | | | |
| | MNL | | 0.000 | 0.000 | 0.000 | 0.000 | 0.000 |
| | RF | *** | | 0.000 | 0.000 | 0.000 | 0.000 |
| NITE | SVM | *** | *** | | 0.007 | 0.000 | 0.000 |
| NTS | NN | *** | *** | ** | | 0.300 | 0.806 |
| | DNN | *** | *** | *** | | | 0.066 |
| | CNN | *** | *** | *** | | | |

Note: ***<0.001, **<0.01, *<0.05

Results: Out-of-sample accuracy



| Dataset | MNL | RF | SVM | NN | DNN | CNN |
|---------|-------|-------|-------|-------|-------|-------|
| OPTIMA | 0.739 | 0.762 | 0.752 | 0.746 | 0.768 | 0.771 |
| NTS | 0.531 | 0.721 | 0.566 | 0.566 | 0.568 | 0.585 |

Conclusions

- The ranking of models is similar in both dataset.
- The highest difference in accuracy in OPTIMA is between MNL and DNN (3.2%)
 O However, in NTS, the highest difference is between MNL and RF (19%).
 - This shows that on datasets designed for RUM models, MNL can achieve a better performance than on ML ones.
- We have shown than RF is the best classifier in terms of accuracy and computational cost.
- The classifiers act in a naive way when the data is not balanced on NTS dataset, predicting only the majority classes and achieving a fictious better accuracy.
- Finally, we evidence the need for other indicators such as the recall of the travel modes, as well as the capability of the model to provide behavioural insights.



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