

Enhancing the convergence speed of line search methods: Applications in Neural Network training



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Introduction

Empirical Risk:

$$R(\omega) = \frac{1}{N} \sum_{n=1}^N f_n(\omega)$$

Introduction

Stochastic gradient descend
(SGD):

$$\omega_{k+1} = \omega_k - \alpha_k \nabla f_n(\omega_k)$$

Batch gradient descend
(GD):

$$\omega_{k+1} = \omega_k - \frac{\alpha_k}{N} \sum_{n=1}^N \nabla f_n(\omega_k)$$

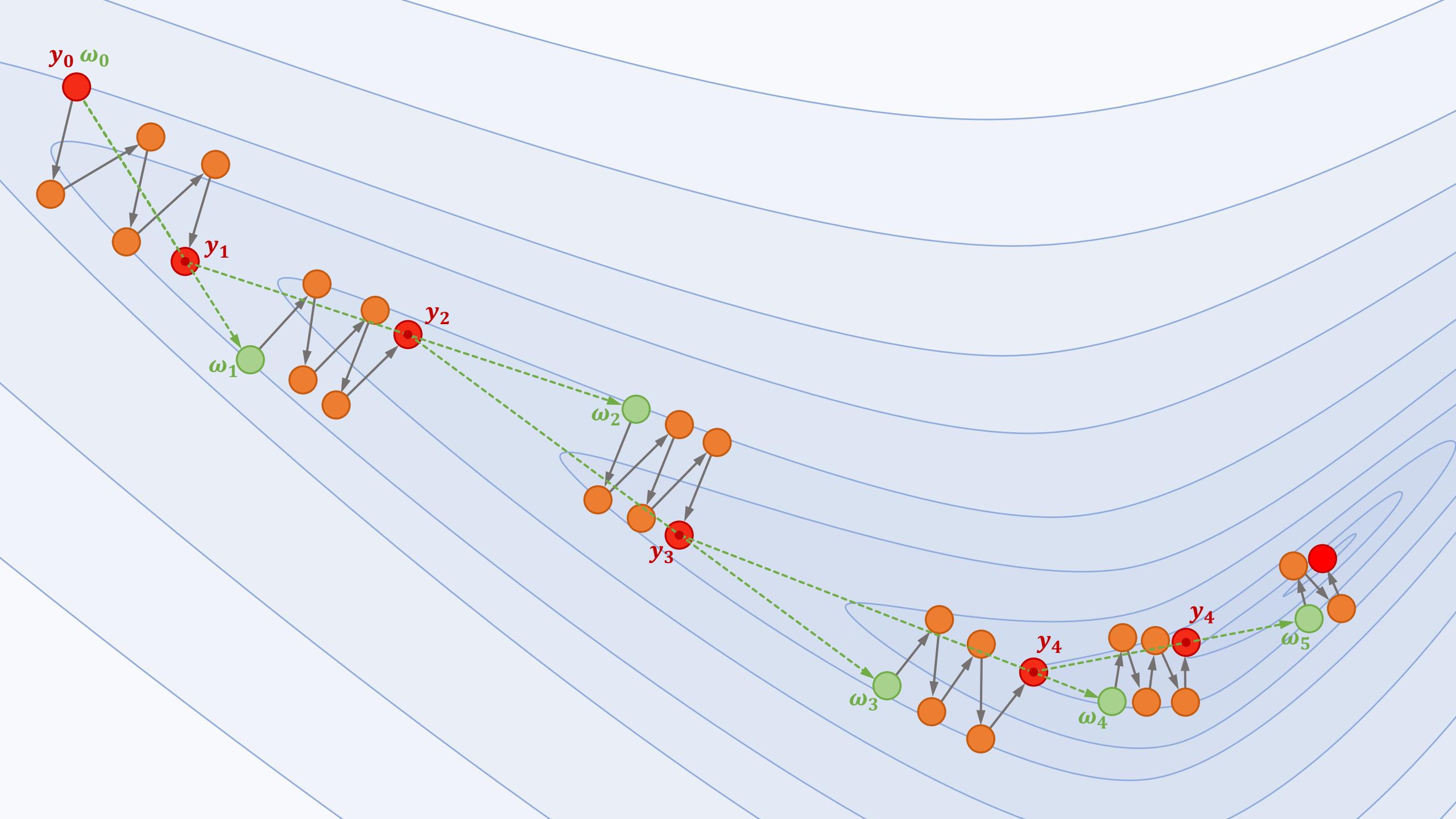
Mini-batch gradient
descend:

$$\omega_{k+1} = \omega_k - \frac{\alpha_k}{|S_k|} \sum_{n \in S_k} \nabla f_n(\omega_k)$$

Introduction

- 1: Choose an initial iterate w_1 .
 - 2: **for** $k = 1, 2, \dots$ **do**
 - 3: Generate a realization of the random variable ξ_k .
 - 4: Compute a stochastic vector $g(w_k, \xi_k)$.
 - 5: Choose a stepsize $\alpha_k > 0$.
 - 6: Set the new iterate as $w_{k+1} \leftarrow w_k - \alpha_k g(w_k, \xi_k)$.
 - 7: **end for**
-

Proposed method



Input : A stochastic line search method \mathcal{A}
 The hyperparameters of the optimisation method
 The objective function F
 Constants $\gamma > 1$, $\theta \in (0, 1)$, α_{\max} , and n_a

Output: The parameter vector ω_t of the optimised model

- 1 Choose an initial guess ω_0 and set $y_0 = \omega_0$, $\alpha_0 = \gamma^{-1}\alpha_{\max}$ and $t = 1$
- 2 **Compute a search direction:** Complete $n_a \geq 1$ epochs using the optimisation algorithm \mathcal{A} , initialising it at the point ω_{t-1} . Store the optimised vector of parameters as y_t . Set the search direction by setting $d_t = y_t - y_{t-1}$
- 3 **Compute the function estimates:** Set $F_t^0 = F(y_{t-1})$
- 4 Set $\mu_0 = \alpha_{t-1}$. Set $\Delta = \theta \|d_t\|_2^2$ and iteration counter $j = 0$
- 5 **if** $F_t^0 - F(y_{t-1} + \mu_0 d_t) \geq \mu_0 \Delta$ **then**
 - /* Increase the step size while the Armijo condition is satisfied */
 - 6 Armijo_satisfied = True
 - 7 **while** Armijo_satisfied **and** ($\gamma \mu_j \leq \alpha_{\max}$) **do**
 - 8 $\mu_{j+1} = \gamma \mu_j$
 - 9 **if** $F_t^0 - F(y_{t-1} + \mu_j d_t) < \mu_j \Delta$ **then**
 - 10 Armijo_satisfied = False
 - 11 **else**
 - 12 $j = j + 1$
 - 13 **else**
 - /* Decrease the step size until the Armijo condition is satisfied */
 - 14 Armijo_satisfied = False
 - 15 **while** not Armijo_satisfied **and** ($1 \leq \gamma^{-1} \mu_j$) **do**
 - 16 $\mu_{j+1} = \gamma^{-1} \mu_j$
 - 17 **if** $(F_t^0 - F(y_{t-1} + \mu_j d_t) \geq \mu_j \Delta)$ **then**
 - 18 Armijo_satisfied = True
 - 19 **else**
 - 20 $j = j + 1$
 - 21 /* Update the parameters */
 - 22 $\alpha_t = \mu_j$
 - 23 $\omega_t = \omega_{t-1} + \alpha_t d_t$
 - 24 If the stop criterion is not satisfied, set $t = t + 1$ and return to step 2

Experiments

Datasets



LPMC

- Single day travel diary data from 2012 to 2015.
- 81,096 surveys with 31 variables.
- After pre-processing, 20 variables selected.



35%



44%



3%



18%



NTS

- ML focused dataset:
 - Data from a Dutch transport survey from 2010 to 2012.
 - Environmental data.
- 230,608 surveys with 16 variables.



4%



55%



24%



17%

Kernel Logistic Regression (KLR)



¹ Martín-Baos et al (2021) *Revisiting kernel logistic regression under the random utility models perspective. An interpretable machine-learning approach.* Transportation Letters

$$U_{in} = V_{in} + \epsilon_{in}$$

$$U_{in} = \text{KLR} + \epsilon_{in}$$

KLR

$$V_i(\mathbf{x} \mid \boldsymbol{\alpha}) = \sum_{n=1}^N \alpha_{in} k(\mathbf{x}_{in}, \mathbf{x})$$

$$[\mathbf{K}_i]_{n,n'} = k(\mathbf{x}_{in}, \mathbf{x}_{in'}) \text{ for } n, n' = 1, \dots, N$$

$$V_i(\mathbf{x} \mid \boldsymbol{\alpha}) = \mathbf{K}_i^{(n)\top} \boldsymbol{\alpha}_i$$

\mathbf{K}_i

n	1	2	3	4	5	6
1	1.0	0.8	0.2	0.0	0.5	0.1
2	0.8	1.0	0.4	0.2	0.6	0.3
3	0.2	0.4	1.0	0.9	0.7	0.5
4	0.0	0.2	0.9	1.0	0.4	0.6
5	0.5	0.6	0.7	0.4	1.0	0.8
6	0.1	0.3	0.5	0.6	0.8	1.0

\mathbf{K}_i

n	1	2	3	4	5	6
1	1.0	0.8	0.2	0.0	0.5	0.1
2	0.8	1.0	0.4	0.2	0.6	0.3
3	0.2	0.4	1.0	0.9	0.7	0.5
4	0.0	0.2	0.9	1.0	0.4	0.6
5	0.5	0.6	0.7	0.4	1.0	0.8
6	0.1	0.3	0.5	0.6	0.8	1.0

	\mathbf{K}_i						α_i
n	1	2	3	4	5	6	
1	1.0	0.8	0.2	0.0	0.5	0.1	0.82
2	0.8	1.0	0.4	0.2	0.6	0.3	0.14
3	0.2	0.4	1.0	0.9	0.7	0.5	-0.26
4	0.0	0.2	0.9	1.0	0.4	0.6	0.91
5	0.5	0.6	0.7	0.4	1.0	0.8	0.74
6	0.1	0.3	0.5	0.6	0.8	1.0	-0.6

\times

$$\mathbb{P}(i \mid \mathbf{K}_n, \boldsymbol{\alpha}) = \frac{e^{V_i}}{\sum_{j=1}^I e^{V_j}} = \frac{e^{\mathbf{K}_i^{(n)\top} \boldsymbol{\alpha}_i}}{\sum_{j=1}^I e^{\mathbf{K}_j^{(n)\top} \boldsymbol{\alpha}_j}}$$

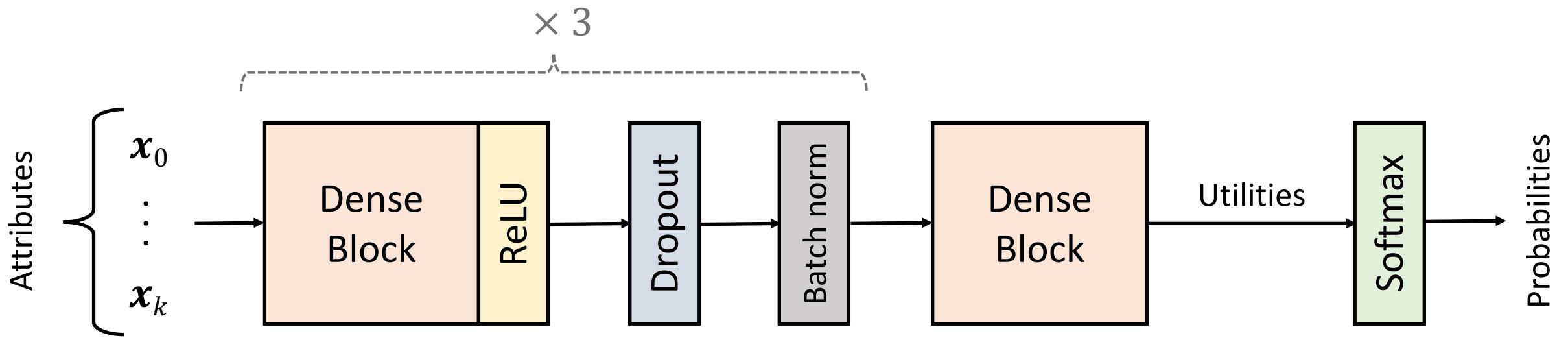
$$\log \mathcal{L}(\boldsymbol{\alpha}) = \sum_{n=1}^N \sum_{i=1}^I y_{in} \log \mathbb{P}(i \mid \mathbf{x}_n, \boldsymbol{\alpha}_i)$$

$$F = -\log \mathcal{L}(\boldsymbol{\alpha}) + \lambda \Omega(\boldsymbol{\alpha})$$

Goodness of
fit

Penalisation
term

Deep Neural Networks (DNN)



$$F = -\sum_{n=1}^N \sum_{i=1}^I y_{n,i} \log \hat{y}_{n,i}$$

Numerical results

GKLR Python package

&

Keras with **tensorflow**



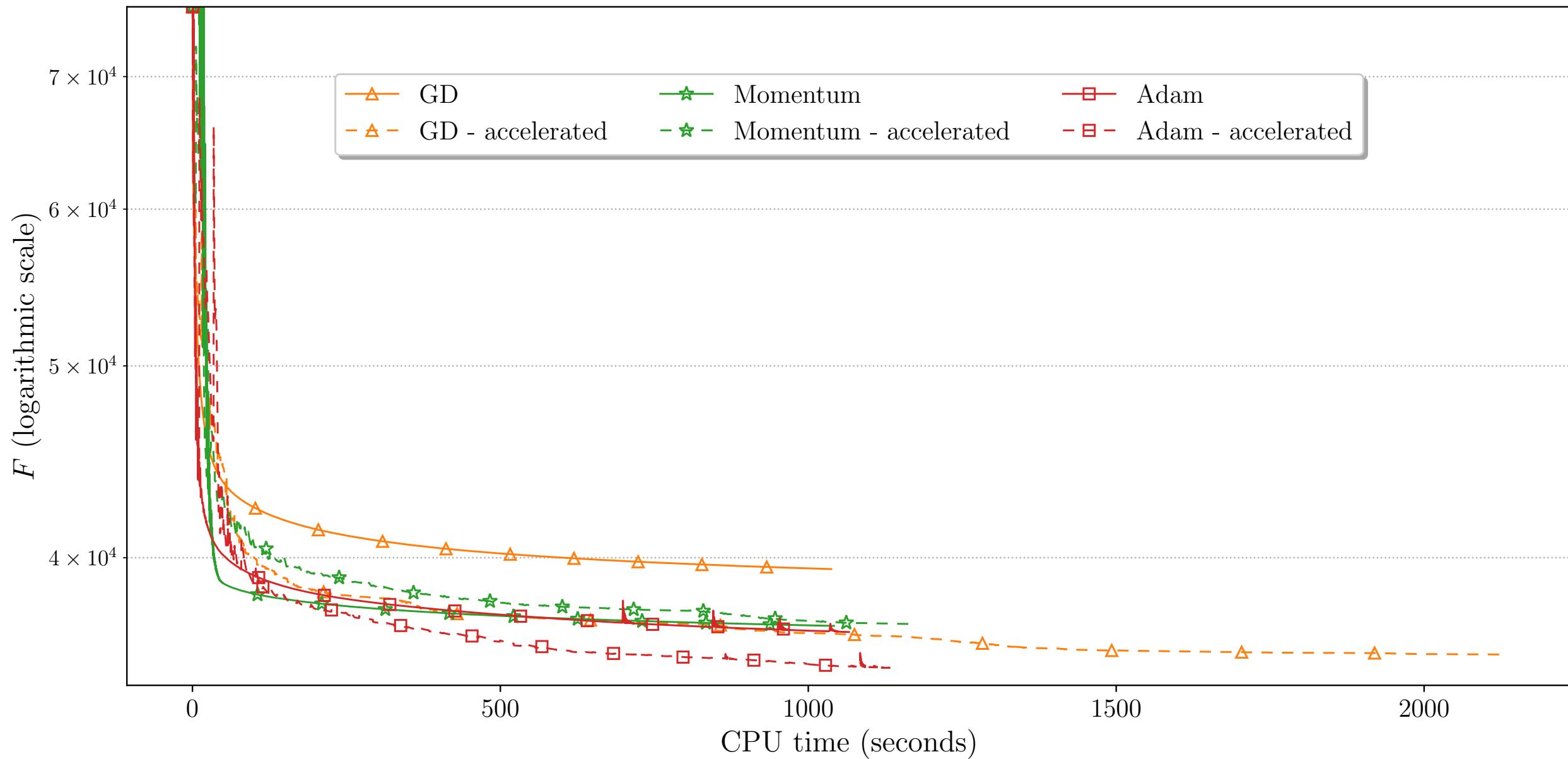
<https://github.com/JoseAngelMartinB/gklr>

Experimental setup

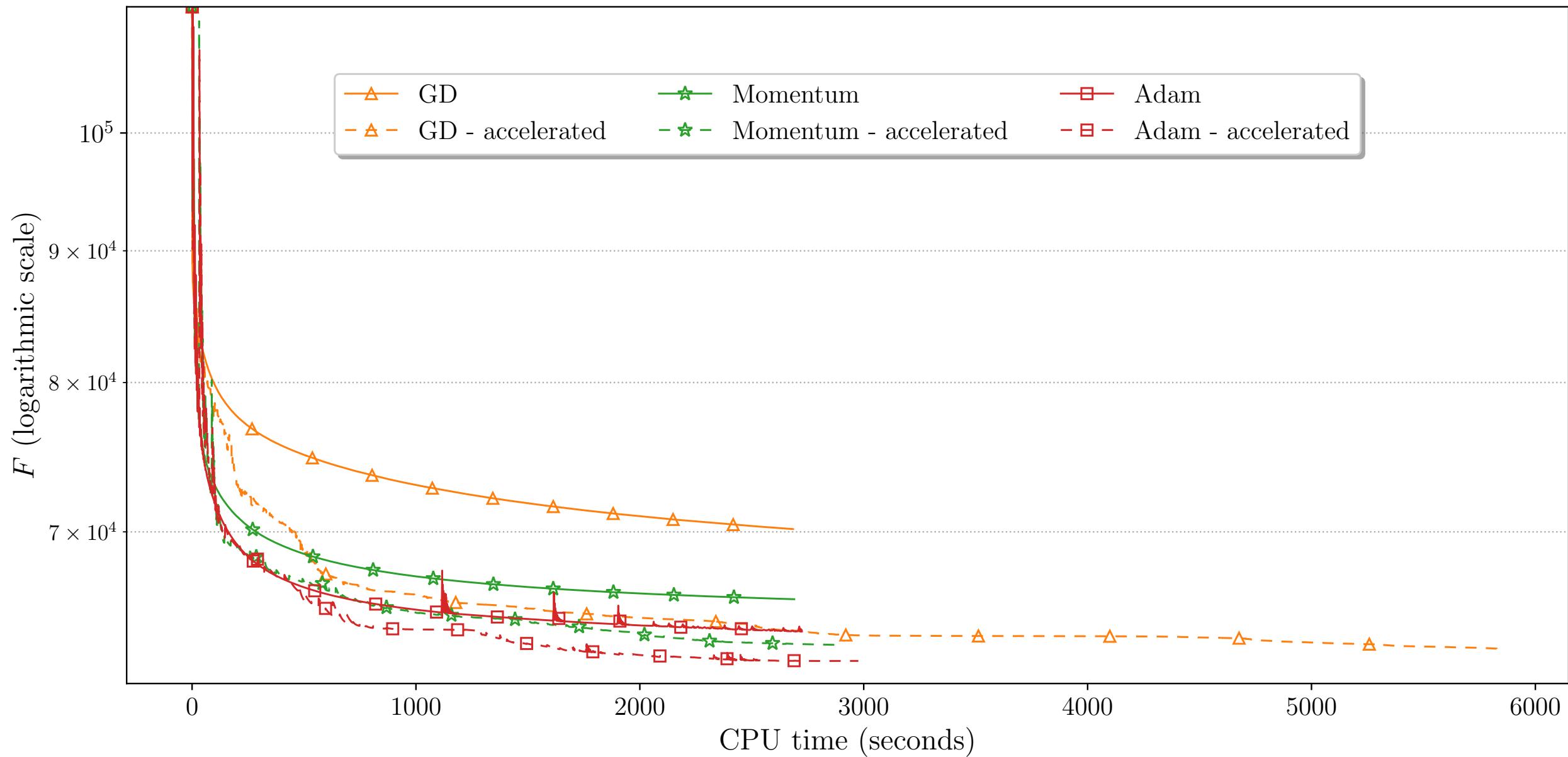


- Ubuntu 20.04 LTS
- 3.8 GHz 12 core AMD Ryzen
- 32 GB of RAM

KLR – Estimation (log-likelihood)



KLR – Estimation (log-likelihood)



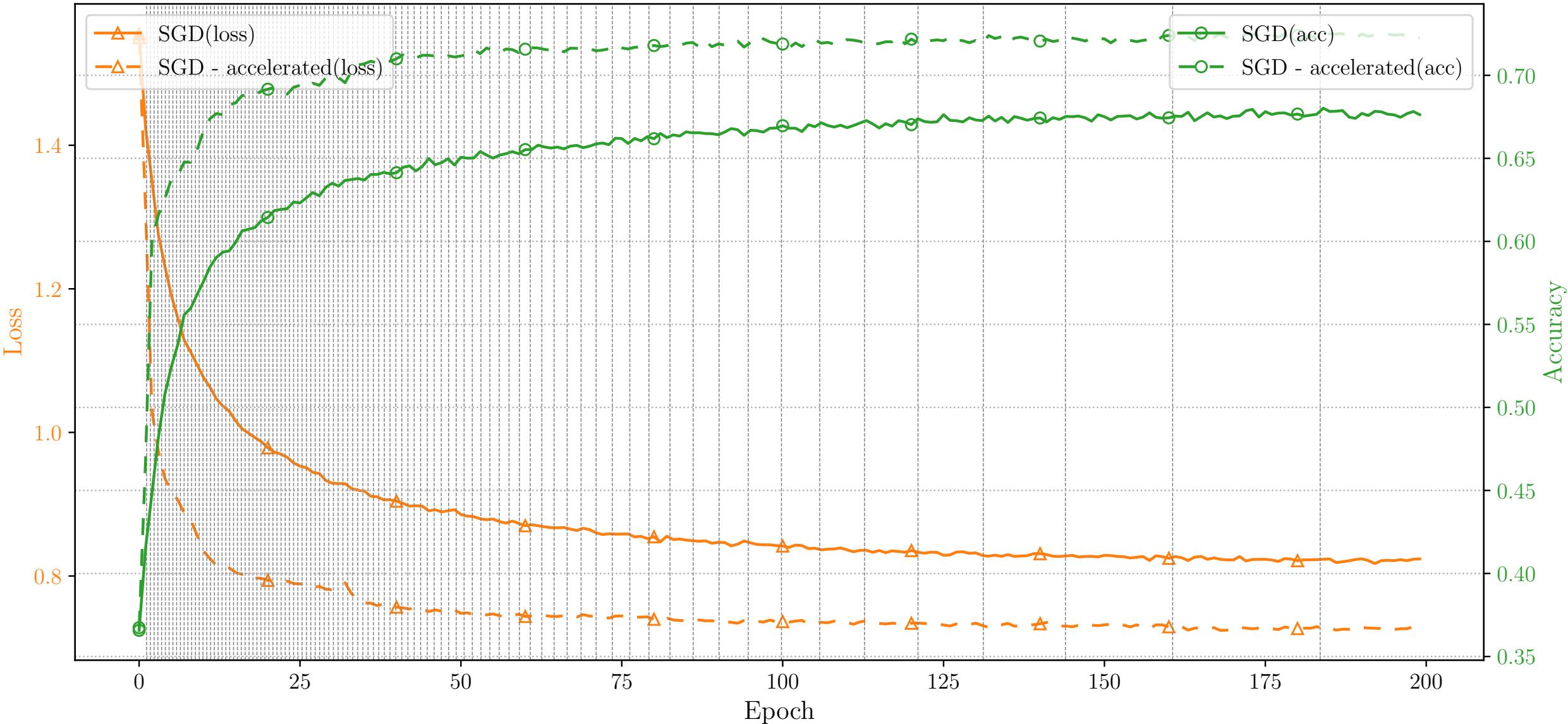
KLR – Estimation comparative

	LPMC		NTS	
	Δ iterations	Δ CPU time (s)	Δ iterations	Δ CPU time (s)
GD	4,711	913.71	4,643	2,249.93
Momentum	–	–	3,777	1,979.45
Adam	3,267	676.14	2,840	1,438.46

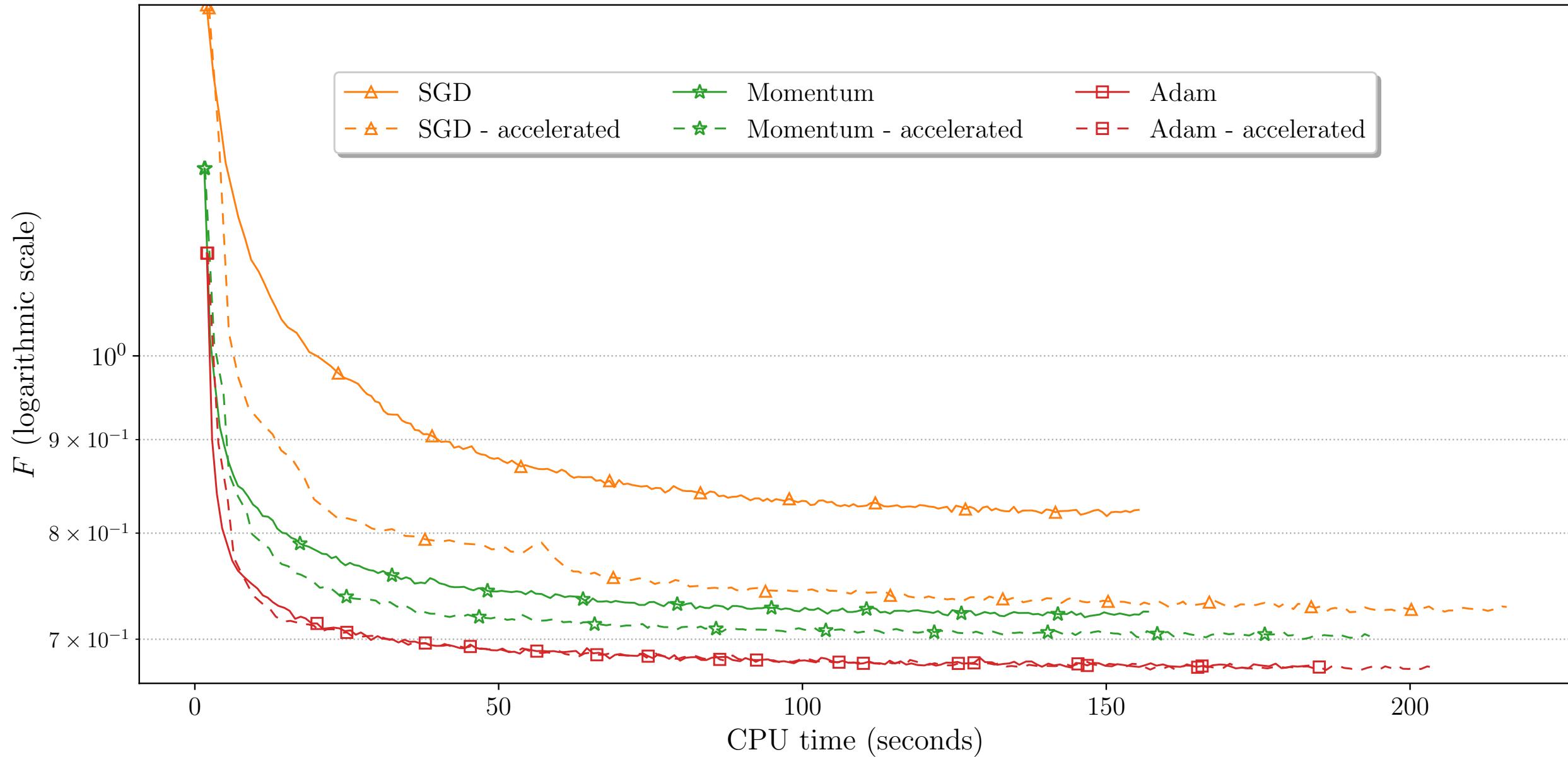
DNN – Estimation for SGD



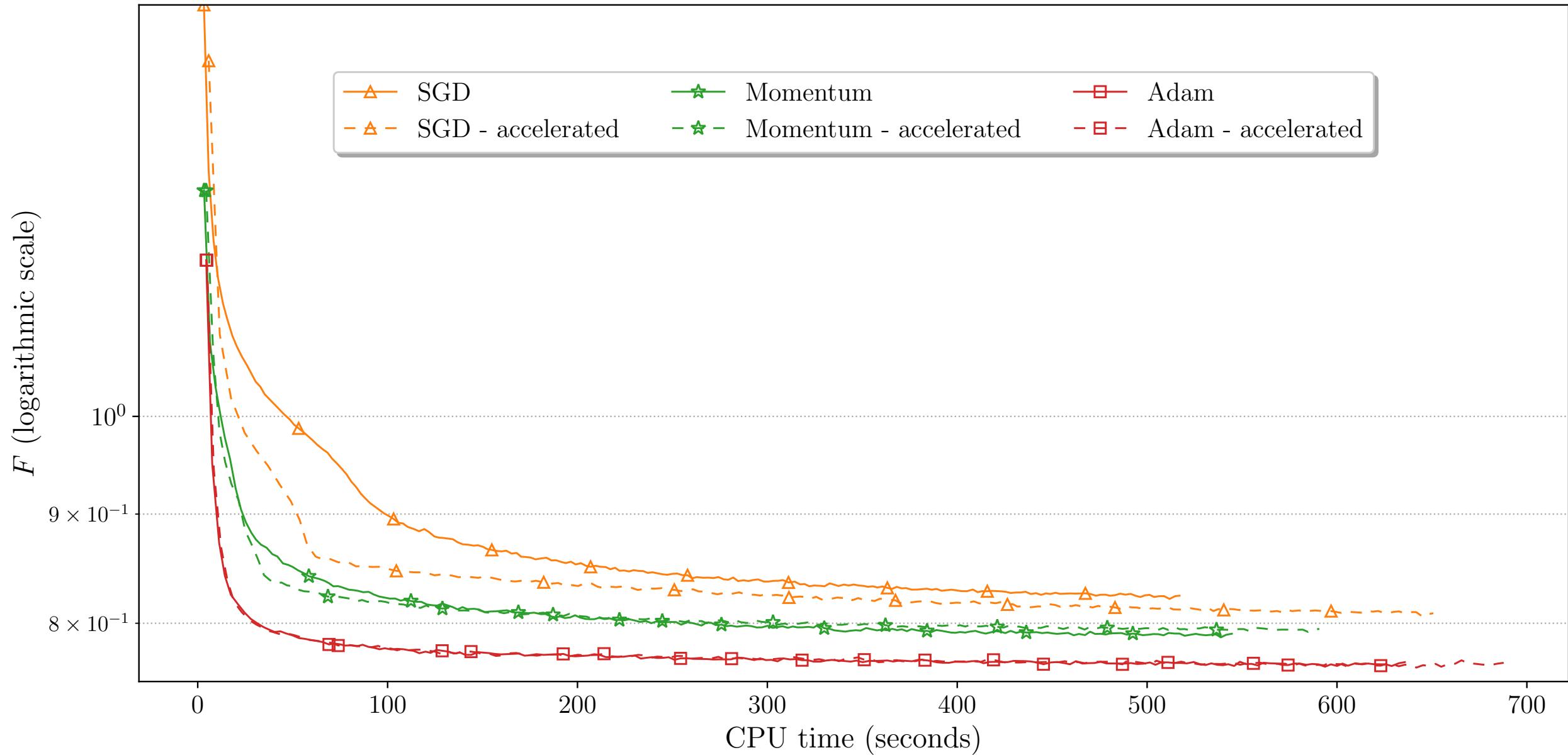
Training and Validation Loss and Accuracy



DNN – Estimation (categorical cross-entropy)



DNN – Estimation (categorical cross-entropy)



DNN – Estimation comparative

	LPMC		NTS	
	Δ epochs	Δ CPU time (s)	Δ epochs	Δ CPU time (s)
SGD	188	132.14	120	206.08
Momentum	170	165.73	—	—
Adam	76	73.32	98	277.69

Conclusions

Conclusions

We have implemented this method in:

KLR

DNN

It seems a promising method

Significantly speeds up the convergence of SGD

This is still a work in progress

More subtly accelerates the convergence of complex methods such as Adam

Future work

When modifying the weights,
the internal moments in
optimizers like Adam should be
updated

Test this technique on larger
problems

Large DNNs with thousands or
millions of data points, such as
images.

Thanks for your attention!

For more information you can contact me at:



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